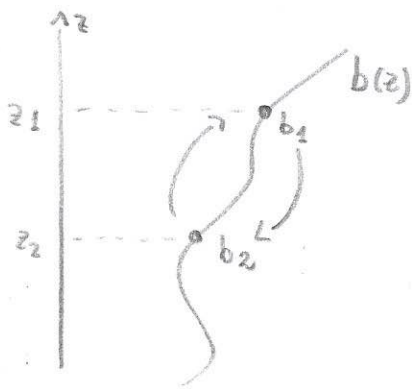


Parcel theory of instabilities

• Gravitational instability

- suppose you have a fluid with variable density in the vertical (only PE in background)
- switch two particles with buoyancy b_1 and b_2



$$\bullet \Delta P = P_{\text{final}} - P_{\text{initial}}$$

$$= -z_1 b_2 - z_2 b_1 - (-z_1 b_1 - z_2 b_2)$$

$$= (z_1 - z_2) b_1 - (z_1 - z_2) b_2$$

$$= \Delta z \Delta b = \Delta z^2 \frac{db}{dz} = \Delta z^2 N^2$$

- ΔP is released if $\Delta b < 0$, $b_1 - b_2 < 0$, $b_1 < b_2$ so $N^2 < 0$!

• Shear - instability

- fluid has variable $b(z)$ and $u(z)$
- two parcels have different densities

$$b_1 = b_2 + \frac{db}{dz} \Delta z$$

- two parcels have different velocities

$$u_1 = u_2 + \gamma \frac{du}{dz} \Delta z$$

$$u_1 = u_2 + \gamma \frac{du}{dz} \Delta z$$

$$u_2 = u_2$$

→
after exchange

$$u_2 = u_2 + (1 - \gamma) \frac{du}{dz} \Delta z$$

• change in PE

$$\Delta P = \Delta z \Delta b$$

• change in KE

$$\begin{aligned} \Delta K &= \frac{1}{2} \left[\left(u_2 + \frac{du}{dz} \Delta z \right)^2 - u_2^2 + \left(u_2 + \gamma \frac{du}{dz} \Delta z \right)^2 + \left(u_2 + (1-\gamma) \frac{du}{dz} \Delta z \right)^2 \right] \\ &= \frac{1}{2} \left[-2u_2 \frac{du}{dz} \Delta z - \left(\frac{du}{dz} \right)^2 \Delta z^2 + 2\gamma u_2 \frac{du}{dz} \Delta z + \gamma^2 \left(\frac{du}{dz} \right)^2 \Delta z^2 \right. \\ &\quad \left. + 2(1-\gamma) u_2 \frac{du}{dz} \Delta z + (1-\gamma)^2 \left(\frac{du}{dz} \right)^2 \Delta z^2 \right] \end{aligned}$$

$$= + \frac{2}{2} \gamma (1-\gamma) \left(\frac{du}{dz} \right)^2 \Delta z^2$$

• instability arises if

$$\Delta P + \Delta K \leq 0$$

(instability always arises if fluid is not stratified)
(turbulence develops and erases any shear)

$$\frac{db}{dz} \Delta z^2 + \gamma(1-\gamma) \left(\frac{du}{dz} \right)^2 \Delta z^2 \leq 0$$

$$\Rightarrow \frac{db}{dz} \leq + \gamma(1-\gamma) \left(\frac{du}{dz} \right)^2 \leq \frac{1}{4} \left(\frac{du}{dz} \right)^2 \quad (\text{N.B. } 0 < \gamma < 1)$$

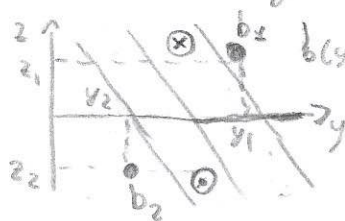
$$Ri = \frac{db/dz}{\left(du/dz \right)^2} \leq \frac{1}{4}$$

• Symmetric instability

• consider a basic state with shear in geostrophic balance

$$f \frac{du}{dz} = - \frac{db}{dy} = -M^2$$

$$\frac{db}{dz} = N^2$$



$$b(y, z) = M^2 y + N^2 z$$

$$\Delta y = y_1 - y_2$$

$$\Delta z = z_1 - z_2$$

$$\Delta b = b_1 - b_2$$

• change in PE

$$\Delta P = \Delta z \Delta b = \Delta z (N^2 \Delta z + M^2 \Delta y)$$

introducing the slopes

$$s_b = -M^2/N^2, \quad s = \Delta z/\Delta y$$

$$[\text{N.B. } s_b = \frac{\Delta z_b}{\Delta y_b}, \quad db = M^2 \Delta y_b + N^2 \Delta z_b = 0]$$

$$\Delta P = N^2 \Delta y^2 s^2 - N^2 s_b^2 \Delta y s \Delta y = N^2 \Delta y^2 s (s - s_b)$$

• change in KE

- without any x variations

$$\frac{\partial u}{\partial t} - f v = \frac{\partial (u - \beta y)}{\partial t} = 0$$

- absolute momentum is conserved

$$\Delta u = \beta \Delta y$$

- no variations in v and w in basic state to generate Δv or Δw by mapping

$$\Delta KE = \frac{1}{2} \left[(u_1 - \beta \Delta y)^2 + (u_2 + \beta \Delta y)^2 - u_1^2 - u_2^2 \right]$$

$$= \frac{1}{2} \left[-2u_1 \beta \Delta y + 2u_2 \beta \Delta y + 2\beta^2 \Delta y^2 \right]$$

$$= (u_2 - u_1) \beta \Delta y + \beta^2 \Delta y^2 = \Delta y^2 \beta \left(\beta - \frac{u_2 - u_1}{\Delta y} \right)$$

- note that

$$u_1 - u_2 = \left(u_2 + \frac{du}{dy} \Delta y + \frac{dw}{dz} \Delta z \right) - u_2 = \frac{du}{dy} \Delta y - \frac{N^2}{f} \Delta z$$

$$\Delta KE = \Delta y^2 \beta \left(\beta - \frac{du}{dy} + s \frac{N^2}{f} \right) = \Delta y^2 \beta \left(\beta - \frac{du}{dy} - \frac{N^2}{f} s s_b \right)$$

• the change in total energy

$$\Delta E = \Delta P + \Delta KE = \Delta y^2 \left[\beta \left(\beta - \frac{du}{dy} \right) - N^2 s s_b + N^2 s (s - s_b) \right]$$

$$= \Delta y^2 \left[\beta \left(\beta - \frac{du}{dy} \right) - N^2 s_b^2 + N^2 (s - s_b)^2 \right]$$

$$= \Delta y^2 \left[\beta \left(\beta - \frac{du}{dy} \right) - \frac{\beta^2}{N^2} \left(\frac{du}{dz} \right)^2 + N^2 (s - s_b)^2 \right]$$

• minimum release of ΔE is along $s = s_b$

$$\Delta E_{\min} = \Delta y^2 \left[\beta \left(\beta - \frac{du}{dy} \right) - \frac{\beta^2}{N^2} \left(\frac{du}{dz} \right)^2 \right] \leq 0$$

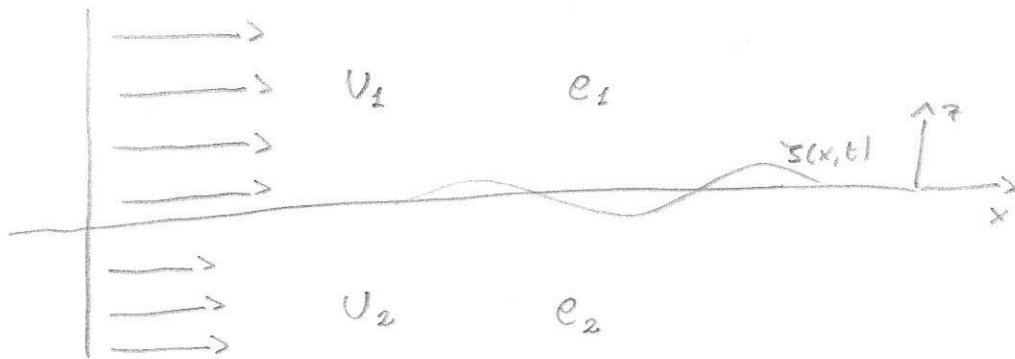
$$\Rightarrow \beta^2 \left(\frac{\Sigma_{\text{tot}}}{\beta} - \frac{1}{Ri_b} \right) \leq 0 \quad \text{or} \quad Ri_b \leq \frac{\beta}{\Sigma_{\text{tot}}} \quad \text{where} \quad \Sigma_{\text{tot}} = \beta - \frac{du}{dy}$$

• note that

$$Ri_b = \frac{N^2}{\left(\frac{du}{dz}\right)^2} = \frac{f^2 H^2}{H^4} \quad \text{the balanced } Ri$$

• relevant for waves in upper ocean where $Ri_b = O(1)$, otherwise $Ri_b \gg 1$
and symmetric instability is not likely to arise

KH instability analysis



- flow is irrotational in both layers

$$\tilde{\Phi}_1 = U_1 x + \phi_1, \quad u_1 = \nabla \phi_1$$

$$\tilde{\Phi}_2 = U_2 x + \phi_2, \quad u_2 = \nabla \phi_2$$

- irrotational flow implies

$$\nabla^2 \tilde{\Phi}_1 = \nabla^2 \phi_1 = 0$$

$$\nabla^2 \tilde{\Phi}_2 = \nabla^2 \phi_2 = 0$$

- b.c. for $|z| \rightarrow \infty$

$$\phi_1 \rightarrow 0 \quad \text{as } z \rightarrow +\infty$$

$$\phi_2 \rightarrow 0 \quad \text{as } z \rightarrow -\infty$$

- interfacial condition (kinematic b.c.)

$$w_1 = \frac{\partial \phi_1}{\partial z} = \frac{D\xi}{Dt} = \frac{\partial \xi}{\partial t} + U_1 \frac{\partial \xi}{\partial x} \quad @ z=0$$

$$w_2 = \frac{\partial \phi_2}{\partial z} = \frac{\partial \xi}{\partial t} + U_2 \frac{\partial \xi}{\partial x} \quad @ z=0$$

- dynamic b.c.

- momentum equations for an irrotational flow

$$\partial_t \nabla \tilde{\Phi} + \frac{1}{2} \nabla (\nabla \tilde{\Phi})^2 = -\frac{1}{\rho} \nabla \tilde{P} - \nabla \rho z$$

- the two layers satisfy

$$\begin{cases} \partial_t \tilde{\Phi}_1 + \frac{1}{2} (\nabla \tilde{\Phi}_1)^2 + \frac{\tilde{P}_1}{\rho_1} + \rho z = C_1 \\ \partial_t \tilde{\Phi}_2 + \frac{1}{2} (\nabla \tilde{\Phi}_2)^2 + \frac{\tilde{P}_2}{\rho_2} + \rho z = C_2 \end{cases}$$

- the pressure is continuous at the interface

$$\tilde{p}_1 = \tilde{p}_2$$

- for basic state

$$e_1 \left(\frac{1}{2} v_1^2 - c_1 \right) = e_2 \left(\frac{1}{2} v_2^2 - c_2 \right)$$

- for perturbations

$$e_1 \left(\partial_t \phi_1 + v_1 \partial_x \phi_1 + g \zeta \right) = e_2 \left(\partial_t \phi_2 + v_2 \partial_x \phi_2 + g \zeta \right) \quad @ z=0$$

• writing solutions in the form

$$(\zeta, \phi_1, \phi_2) = (\hat{\zeta}(z), \hat{\phi}_1(z), \hat{\phi}_2(z)) e^{ik(x-ct)}$$

$$\begin{cases} \hat{\phi}_{1,zz} - k^2 \hat{\phi}_1 = 0, & \hat{\phi}_1 = A e^{-kz} \\ \hat{\phi}_{2,zz} - k^2 \hat{\phi}_2 = 0, & \hat{\phi}_2 = B e^{kz} \end{cases}$$

• kinematic b.c.

$$(-ikc + ikv_1) \hat{\zeta} = \hat{\phi}_{1,z} = -Ak \quad \Rightarrow A = -i(v_1 - c) \hat{\zeta}$$

$$(-ikc + ikv_2) \hat{\zeta} = \hat{\phi}_{2,z} = Bk \quad \Rightarrow B = i(v_2 - c) \hat{\zeta}$$

• dynamic b.c.

$$e_1 \left(-ikc \hat{\phi}_1 + ikv_1 \hat{\phi}_1 + g \hat{\zeta} \right) = e_2 \left(-ikc \hat{\phi}_2 + ikv_2 \hat{\phi}_2 + g \hat{\zeta} \right) \quad @ z=0$$

$$e_1 \left(i k (v_1 - c) (-i) (v_1 - c) \hat{\zeta} + g \hat{\zeta} \right) = e_2 \left(i k (v_2 - c) i (v_2 - c) \hat{\zeta} + g \hat{\zeta} \right)$$

$$e_1 (k(v_1 - c)^2 + g) = e_2 (-k(v_2 - c)^2 + g)$$

$$k e_1 (v_1 - c)^2 + k e_2 (v_2 - c)^2 = (e_2 - e_1) g$$

$$k(e_1 + e_2) c^2 - 2k(e_1 v_1 + e_2 v_2) c + k e_1 v_1^2 + k e_2 v_2^2 - (e_2 - e_1) g = 0$$

$$c = \frac{k(e_1 v_1 + e_2 v_2) \pm \sqrt{k^2(e_1 v_1 + e_2 v_2)^2 - k(e_1 + e_2)(k e_1 v_1^2 + k e_2 v_2^2 - (e_2 - e_1)g)}}{k(e_1 + e_2)}$$

$$= \frac{e_1 v_1 + e_2 v_2}{e_1 + e_2} \pm \sqrt{\frac{g}{k} \frac{e_2 - e_1}{e_2 + e_1} - e_1 e_2 \left(\frac{v_1 - v_2}{e_1 + e_2} \right)^2}$$

• the flow is unstable if

$$\frac{g}{k} \frac{e_2 - e_1}{e_2 + e_1} < e_1 e_2 \frac{(v_1 - v_2)^2}{(e_1 + e_2)^2}$$

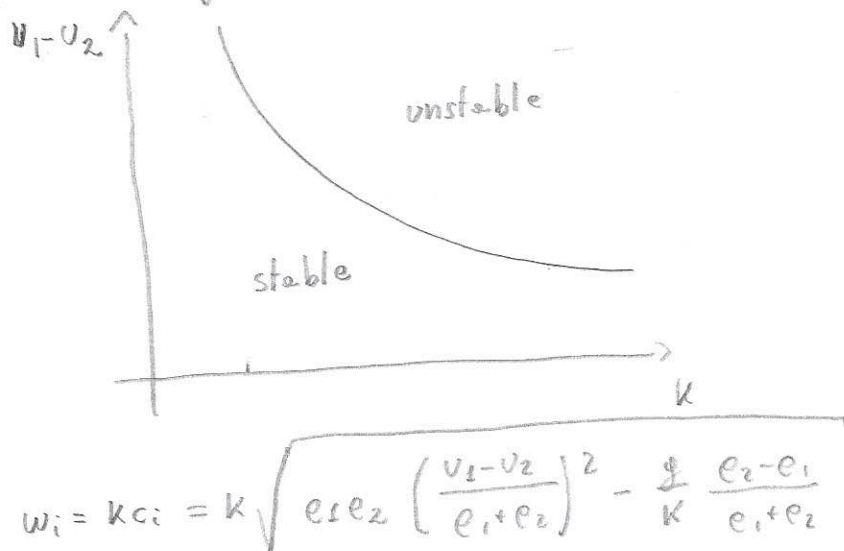
$$g(e_2^2 - e_1^2) < k e_1 e_2 (v_1 - v_2)^2$$

• if $e_2 = e_1$ flow is always unstable

• compare with KH criterion for weak density variations $e_2 = e_1 + \epsilon$

$$g \frac{\Delta e}{e^2} < \frac{1}{2} k \Delta v^2$$

• instability curve



Instability of continuously stratified parallel flows (Kelvin-Helmholtz instability)

- basic state $U(z)$

- perturbations

$[U+u, 0, w]$ Squire's theorem shows that 2D perturbations are most unstable

$P+p$

$B+b$

- perturbation equations

$$\begin{cases} \frac{\partial u}{\partial t} + U \frac{\partial u}{\partial x} + w \frac{dU}{dz} = -\frac{\partial p}{\partial x} \\ \frac{\partial w}{\partial t} + U \frac{\partial w}{\partial x} = -\frac{\partial p}{\partial z} + b \\ \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial b}{\partial t} + U \frac{\partial b}{\partial x} + w \frac{dB}{dz} = 0 \end{cases}$$

$\underbrace{\frac{dB}{dz}}_{N^2}$

- introducing the streamfunction

$$u = -\psi_z$$

$$w = \psi_x$$

- perturbation equations become

$$\begin{cases} -\psi_{zt} - U \psi_{xz} + \psi_x U_z = -p_x \\ \psi_{xt} + U \psi_{xx} = -p_z + b \\ b_t + U b_x + N^2 \psi_x = 0 \end{cases}$$

- ignoring lateral boundaries we can express solutions in the form

$$[b, p, \psi] = [\hat{b}(z), \hat{p}(z), \hat{\psi}(z)] e^{iK(x-ct)}$$

where K must be real for the flow to remain bounded

$c = c_r + ic_i$ can be complex ($c_i = 0$ waves, $c_i \neq 0$ unstable modes)

• perturbation equations

$$\begin{cases} (U-c) \hat{\psi}_z - U_z \hat{\psi} = +\hat{p} \\ (U-c) k^2 \hat{\psi} = +\hat{p}_z - \hat{b} \\ (U-c) \hat{b} + N^2 \hat{\psi} = 0 \end{cases}$$

• taking z -derivative of first equation and subtracting second equation

$$U_z \hat{\psi}_z + (U-c) (\partial_z^2 - k^2) \hat{\psi} - U_{zz} \hat{\psi} - U_z \hat{\psi}_z + \frac{N^2}{U-c} \hat{\psi} = 0$$

Taylor-Golstein equation

• boundary conditions of no-normal flow at top and bottom boundaries

$$\Psi(0) = \Psi(H) = 0$$

• introduce new variable

$$\phi = \frac{\hat{\psi}}{\sqrt{U-c}} \quad \text{or} \quad \hat{\psi} = (U-c)^{1/2} \phi$$

• T-G equation reduces to

$$\hat{\psi}_z = (U-c)^{1/2} \phi_z + \frac{1}{2} \frac{U_z}{(U-c)^{1/2}} \phi$$

$$\hat{\psi}_{zz} = (U-c)^{1/2} \phi_{zz} + \frac{U_z}{(U-c)^{1/2}} \phi_z + \frac{1}{2} \frac{U_{zz}}{(U-c)^{1/2}} \phi - \frac{1}{4} \frac{U_z^2}{(U-c)^{3/2}} \phi$$

$$(U-c) \left[(U-c)^{1/2} \phi_{zz} + \frac{U_z}{(U-c)^{1/2}} \phi_z + \frac{1}{2} \frac{U_{zz}}{(U-c)^{1/2}} \phi - \frac{1}{4} \frac{U_z^2}{(U-c)^{3/2}} \phi - k^2 (U-c)^{1/2} \phi \right] + \left[\frac{N^2}{U-c} - U_{zz} \right] (U-c)^{1/2} \phi = 0$$

$$\frac{d}{dz} \left((U-c) \phi_z \right) + \left(-\frac{1}{2} U_z z - \frac{1}{4} \frac{U_z^2}{(U-c)} - k^2 (U-c) + \frac{N^2}{U-c} \right) \phi = 0$$

• multiplying by the complex conjugate ϕ^* and integrating in the vertical

• here it goes

$$\int_0^H \left[(U-c) (-|\phi_z|^2) - k^2 (U-c) |\phi|^2 \right] dz + \\ + \int_0^H \frac{N^2 - \frac{1}{4} U_z^2}{U-c} |\phi|^2 dz + \frac{1}{2} \int_0^H U_{zz} |\phi|^2 dz = 0$$

• the imaginary part of this expression is

$$c_i \int_0^H \left[|\phi_z|^2 + k^2 |\phi|^2 \right] dz + c_i \int_0^H \frac{N^2 - \frac{1}{4} U_z^2}{|U-c|^2} |\phi|^2 dz = 0$$

• if $N^2 > \frac{1}{4} U_z^2$ then $c_i = 0$

• if $N^2 < \frac{1}{4} U_z^2$ then c_i can be $\neq 0$

$R_i = \frac{N^2}{U_z^2} < \frac{1}{4}$ is a necessary (but not sufficient) condition for instability!

$R_i = \frac{N^2}{U_z^2} > \frac{1}{4}$ guarantees stability

• notice that R_i can fall below $\frac{1}{4}$ only in a limited region for instability to possibly develop